

RossAutomation

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Supported Editors

These setup instructions apply to any editors using the Ross Automation editor protocol.

Requirements

- Editor Interface Software Option
- Ethernet Cable

Port Connections

	Switcher		Editor
Communications	PERIPH Port (female)	⇒	Network TCP Port

Switcher Setup

- 1. Press HOME ⇒ Setup ⇒ Installation ⇒ Com Setup ⇒ Type.
 - Use the **Com Port** knob to select the **PERIPH** *X* port that you connected the Ross Automation editor to.
 - Use the **Device** knob to select **Editor**.
- 2. Press Editor Protocol.
 - Use the **Device** knob to select **RossAuto**.
- 3. Press Com Type.
 - Use the Type knob to select Network TCP.
- 4. Press Com Setting.
- 5. Use the Client/Server knob to select Server.
 - In the Local IP Address field, enter 0.0.0.0.
 - Leave the Local IP Port field as is
- **6.** Press **HOME** \Rightarrow **Confirm**.

Note: The **Editor** remote enable, or button, must be turned on for the editor to control the switcher (**Home** \Rightarrow **More** \Rightarrow **Remote Enables**).

Device Setup

Ensure the port on the Ross Automation editor that is connected to the switcher is configured for Network TCP.

Compatibility

Editor	Version
RossAutomation	

Switchers	
Synergy 1 SD	
Synergy Series SD	
Synergy MD/X	
Vision MD/X	
Vision QMD/X	16.0a
Vision MultiPanel Support	
Port Expanders	
BSS4	*
Comtrol DeviceMaster	×



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