RossAutomation

Supported Editors

These setup instructions apply to any editors using the Ross Automation editor protocol.

Requirements

- Editor Interface Software Option
- Ethernet Cable

Port Connections

	Switcher		Editor
Communications	PERIPH Port (female)	⇨	Network TCP Port

Switcher Setup

1. Press **HOME** ⇨ **Setup** ⇨ **Installation** ⇨ **Com Setup** ⇨ **Type**.

   - Use the **Com Port** knob to select the **PERIPH X** port that you connected the Ross Automation editor to.
   - Use the **Device** knob to select **Editor**.

2. Press **Editor Protocol**.

   - Use the **Device** knob to select **RossAuto**.

3. Press **Com Type**.

   - Use the **Type** knob to select **Network TCP**.

4. Press **Com Setting**.

5. Use the **Client/Server** knob to select **Server**.

   - In the **Local IP Address** field, enter **0.0.0.0**.
   - Leave the **Local IP Port** field as is

6. Press **HOME** ⇨ **Confirm**.

*Note: The **Editor** remote enable, or button, must be turned on for the editor to control the switcher (**Home** ⇨ **More** ⇨ **Remote Enables**).*

Device Setup

Ensure the port on the Ross Automation editor that is connected to the switcher is configured for Network TCP.

Compatibility

Editor	Version
RossAutomation	--

Switchers	
Synergy 1 SD	--
Synergy Series SD	--
Synergy MD/X	--
Vision MD/X	--
Vision QMD/X	16.0a
Vision MultiPanel Support	--
Port Expanders	
BSS4	✖
Comtrol DeviceMaster	✖

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